P04-2 ID132 A MODELLING OF ELBOW FLEXION AND CALCULATION OF MUSCLE MOMENT AND THE REACTION FORCE ON ELBOW USING ADAMS SOFTWARE

Ilbeigi. Saeed, Ramezani. Hamid, Bakhshi. Elaheh

Physical Education & Sport Science Faculty, Birjand University, Birjand, Iran

In this research elbow flexion has been analysed and the moment of muscles and the reaction force exerted on the elbow is calculated in the range of motion. The moment of muscles indicate the performance of movement and the reaction force of the joint is believed to be one of the most important causes of damage, something which hasn't been studied thoroughly enough in previous researches. To that end, we use ADAMS software which is one of the most powerful ones available in dynamics analyses. The results indicate that the maximum torque of the arm occurs at 96 degrees and it decreases in the beginning and the end of flexion. The reaction force of the elbow in the beginning of motion is at maximum amount and then decreases to 107 degrees, and from that point on it increases up to the end of the motion. These results indicate that the optimum range of elbow flexion occurs in the mid-range of flexion, approximately at 58-140 degrees.

KEY WORDS: modelling, moment, reaction force, elbow flexion.

INTRODUCTION: considering the progress in human sciences, it seems that, it is possible to use other sciences, specially engineering sciences, mutually. Nowadays, using software in the field of engineering is very common. Moreover, one of the important uses of these softwares is in modelling. Because of the developments of sport biomechanics it seems that making use of these kinds of engineering softwares can help to improve it. Some of the applications of sport modelling are sport equipment designing, kinematic and kinetic human movement analyzing, understanding the injury mechanism of joints and tissues, and finally the development of sport activities performances.

Previous research studies show that human movement modelling software has been rarely used and sometimes it shows a great difference in comparison to other analysing methods such as motion capture, electromyography and empirical research. The major advantages of this approach include reduction in terms of cost and time without needing to use human and equipment and increase the accuracy of research data. In our study, muscles moment and reaction force exerted on the elbow joint were studied. Joint torque help us determine the range of strengths and weakness of muscles and the reaction force of the elbow joint is potentially capable of causing harm to the joint. Figure 1 shows the elbow joint reaction force. This force is measured by the balance of forces and moments. This force represents the forces exerted on the ligaments and joint capsule.





METHODS: the method of this study is to model the elbow joint using ADAMS software. The application is made by the MSC Software Corporation and is a powerful tool for analyzing kinetic & kinematic analysis and is widely used in science and engineering. The first step for modelling the movement of flexion is to build the parts of the arm. These parts are made by the software toolbox and making use of appropriate geometric shapes and anthropometric data table1. In the second step the organs must be bound and in this research the connections between humerus and ulna are made using hinged joints. In the third step, the muscular forces obtained from the EMG data are applied with respect to the specified ratio in Table 2. Then, in the fourth step the software application is provided with the required information such as moment, the joint reaction force etc. And finally the motion is run in the range 0-150 degrees and as a result the software reports the results in the form of a chart that was requested in the last step. Addition the base of calculation of software is the laws of physics and dynamic. The process in like to manual calculation of laws dynamic that the software perform quickly and easily.

Parameters evaluation for rigid body modelling.(ZHANG.lin-lin and et al 2011)				
Segment	Hummers	Ulna	Radius	
m(kg)	1.81	0.79	0.79	
h(cm)	27.4	38.253	38.253	
r(cm)	4.165	2.365	2.365	
lxx (kg.m2)	121.089	97.438	97.438	
lyy(kg.m2)	121.089	97.438	97.438	
lzz (kg.m2)	15.699	2.209	2.209	

Table 1

 $Ixx=Iyy=m (r^2/4+h^2/12)$ and $Izz=mr^2/2$

Table2				
Ratio of forces exerted by muscles during elbow flexion. (ZHANG.lin-lin and et al 2011)				
Muscle name	F(N) From EMG	Percentage of producing force for flexion		
Biceps	137	39%		
Brachialis	167	48%		



Figure2: Upper limb biomechanical model in ADAMS software

RESULTS: In this research the torque of each muscle and the total moment throughout the range of motion is obtained. The maximum moment of biceps occurs at 86 degree and brachialis at 118 degree and brachioradialis at 91 degrees and therefore the total moment of three muscles was measured at an angle of about 96 degrees.





One important result of the study is to investigate the reaction force exerted on the elbow joint. This force is potentially capable of causing damage to the joint. The study showed that the reaction force is at maximum amount at the beginning and then reduces to a 107-degree angle and then increases toward the end of the motion.





The figures above show different levels of moment and joint reaction force in the range of motion which is due to changes of muscle angle. If the two components of horizontal and vertical forces exerted on the forearm muscles are divided, we observe that only the component of motion perpendicular to the forearm is capable of producing motion And horizontal components of the muscle does not produce any work and compress bones together and as a result will produce a reaction force.

Figure.5 shows the total vertical component muscle force, in comparison with horizontal component muscle force. This chart indicates that the vertical component is more than horizontal component in the mid range and the muscles of elbow flexion have high performance in the 58-140 degree of flexion so it is suggested for rehabilitation of arm after damaging and designing ergonomic conditions.



Figure5: Comparison of horizontal and vertical components of the muscle force of elbow flexion in elbow flexion range of 0 to 150



Figure6: A comparison of the overall sum of the vertical and horizontal muscle forces in flexion of the elbow. The total amount of vertical and horizontal force is 38 percent to 62 percent respectively.

The total amount of muscle forces in the vertical and horizontal components is the result of the integration of curve 5 in figure 6.

Figure 6 shows that the 38% of the energy of the muscles turn to work and the rest is wasted by turning into reaction force and other forms of energy such as heat and friction. In other words, only 38% of muscle force can produce motion and movement in the skeletal system.

DISCUSSION: This study shows that the maximum torque of the elbow occures at an angle of approximately 96 degrees which is in agreement with the results of other researchers. ZHANG.lin-lin et al (2011) in their research obtained the approximate maximum moment at an angle of 90 degrees although their graph indicates that maximum moment occurs at an angle more than 90 degrees. Felipe Pivetta Carpes et al (2012) evaluated asymmetries in elbow torque output between preferred and non-preferred limbs. They obtained moment curve in five angles with the maximum moment at 90 degrees. It should be noted that moment curve was calculated only at specific angles. And torque was not calculated at an angle between 90 and 120. If moment values had been calculated at more angles, moment curve and maximum angle could have been different.

Another result of this study is the optimal range of elbow flexion which occurred at an angle between 58 and 140 degrees and the 38% mechanical efficiency of muscles can also be noted. It was so strange to us why the musculoskeletal system of the arm is so inefficient. Has the creator of the universe made a mistake? Morry's research answers this obscurity. Morry et al (1981) obtained the range of flexion for fifteen essential daily activities by using an electro goniometer. Most of the activities studied in this project were carried out at a mid-range of 100 degrees of elbow flexion (from 30 to 130 degrees). This indicates that the musculoskeletal system of the arm is optimally capable of performing essential daily activities.

CONCLUSION: The main results of the analysis and modelling of elbow flexion movement is the evaluation of the efficiency of the elbow flexion muscles in the range of motion. The results show that maximum muscle moment of the arm occurs at an angle of 96 degrees and at the start and end of the flexion is much less. Moreover, the reaction force of the elbow which is one of the most important potential damage to the joint is at the minimum in the mid-range of motion(107degree). Therefore, Combining these two results show that the efficiency of flexion is in the range of 58 to 140 degrees.

REFERENCES:

Lin-lin.ZHANG, Jian. ZHOU, Xi-an. ZHANG, Cheng-tao. WANG, (2011), Upper Limb Musculo-Skeletal Model for Biomechanical Investigation of Elbow Flexion Movement, J. Shanghai Jiaotong Univ. (Sci.), 16(1): 61-64

Pivetta Carpes. Felipe, Marcel Geremia. Jeam, Paula Barcellos Karolczak. Ana, Diefenthaeler. Fernando, Aurélio Vaz. Marco, (2012), Preference and torque asymmetry for elbow joint, Motriz, Rio Claro, v.18 n.2, p.319-326

MORREY.B. F, ASKEW.L. J, AN. K. N and CHAO. E.Y, (1981), a Biomechanical Study of Normal Functional Elbow Motion, The Journal of Bone and Joint Surgery, 872