BIOMECHANICAL ANALYSIS OF VERTICAL JUMP PERFORMANCE OF VOLLEYBALL PLAYERS

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The purpose of this study was to provide some reference in the vertical jump performance of professional volleyball player. It was expected that, the main biomechanical factors relative directly to the jump height of professional volleyball player can be found through the synchronic test of ground reaction force and video technique performance.

KEY WORDS: volleyball, vertical jump performance, biomechanics

INSTRUCTION: As a basic form of jump, the vertical jump performance (VJP) has been studied by researchers for decades. Recently, a large body of literature has been published in this field. According to James J. Dowling and Lydia Vamos (1993), the jump height is highly related to the maximum positive power (r=.928, p<.01), and also related to the maximum force (r=.519, p<.01). Armin Kibele (1998) addressed an article regarding a methodological point in standard test of VJP in Laboratory. Luis F. Aragon-Vargas and M.Melissa Gross (1997) furnished us a 4-lever biomechanical variable system to research VJP. The work of these scientists provided us some aspects to understand the mechanism of VJP. However, few articles use the professional volleyball players directly as research subjects. The purpose of this study is to submit some reference in the VJP of professional volleyball player. It is hoped that, the main biomechanical factors relative directly to the jump height of professional volleyball player will be found through the synchronic test of ground reaction force and video technique performance.

METHODS: 5 Chinese professional male volleyball players with national level, age 22.5±3.8,

height 1.94±.06m, weight 74.2±4.9kg, were selected to perform the vertical jump in

Biomechanics Laboratory. In order to simulate the real jump performance during the volleyball competition, each player was instructed to complete 2 maximum vertical jumps with arm swing from a static, upright posture. Because of a mistake about the recording, only 9 VJP were recorded in Kistler platform system in 200Hz for ground reaction force and synchronically videotaped with PANASONIC AG-DP200E recorder in 50Hz in sagittal plane. The distance from focus was about 10m. The height of the focus is about 1.4m. The video pictures were digitized and analyzed on Engine Video Analysis Performance System. A second-order Butterworth digital filter was used to smooth the derived data with cutoff frequency 8Hz for displacement variables (angular and linear displacements) and 6Hz for velocity variables (angular and linear velocities). The final data were dealt statistically (n=9)

with 586 computer. A Student's t test was performed to test the differences between the first and the second peak of force. Because the ground reaction force at the beginning of VJP is defined as zero, all force and force impulse variables in this paper are the values including the body weight.

Synchronic method for variable analysis. The video sample frequency is 50Hz. But the ground reaction force is sampled in 200Hz. In order to make the variables from video and those from the reaction force in the same point of time, we should define the synchronic point (or the datum line). In general this line could be given by machine. However, we could solve the synchronic problem easily based on the Newton law and the mathematical knowledge. If we think the whole human body as one point, from the Newton law, we have:

$$F_{y}$$
- W = ma(1)

Where, m is the mass of the body. a is acceleration of the body center. W is the body weight. From equation (1), we can have:

$$\mathsf{F} = \mathsf{m} \frac{dv}{dt} \qquad(2)$$

At the beginning of performance, the subject stands on the force platform, the ground reaction force is equal to W. However, we make the reaction F at this point zero. Thus, in formula (2), F (= F_y --W) is including the human weight W. According to the differential calculus, V gets (negative or positive) maximum when F is equal to zero. It means that at the point b in figure 1a, the vertical velocity of CM reaches negative maximum while at the point of c, the velocity gets positive maximum. Because it is easy for us to get the positive maximum velocity of CM (see figure 1b) from the digitized video data, we could choose the vertex point of Velocity-time curve as a synchronic point. Thus the point c in figure 1a is in the same time as the point c' in figure 1b. In this paper, the point c is selected as a datum line. The time variables are all relative to this line. The time value of point c (or c') is defined 0.



Figure 1 - Typical ground reaction force and vertical CM velocity of VJP of volleyball player; (a) reaction force-time curve; (b) vertical CM velocity-time curve.

Glossary of Terms

 H_d --- downward motion of CM relative to static, upright posture (m).

H_j---- jump height of CM relative to static, upright posture (m).

W--- body weight (kg)

 V_y ---the maximum vertical velocity of CM (m/s).

V_{hand} --- the maximum velocity of hand (m/s).

 P_0 , P_1 , P_2 -- the negative maximum force, the first positive peak of force, and the second positive peak of force (N).

 p_0 , p_1 , p_2 – the rate of P_0 , P_1 , P_2 over W.

 I_1 , I_2 — the impulse of ground reaction including the body weight (Ns).

 T_0 , T_1 , T_2 —the time of P_0 , P_1 , P_2 point relative to the datum line (ms)

 T_S , T_H , T_K , T_A ——the time when the joint of shoulder(S), hip(H), knee(K), ankle(A) begin to accelerate relative to the datum line (ms).

T_a——the time of the acceleration phase (ms)

 T_n ----- the time of no acceleration phase during the takeoff period (ms).

 ω ——the maximum joint angular velocity (deg/s).

RESULTS AND DISCUSSION: The ground reaction force: The variables about ground reaction forces of all subjects are presented in Table 1. The correlation r in this Table means the correlation with the jump height of CM. It is shown that the lost weight in the downward motion is about half of body weight, while the maximum positive force is 1.77 times of body weight.

The typical force-time curve of VJP is a double peak curve. The first peak P_1 is shown the greatest correlation (r=.87, p<.01). The second peak of force is also correlated with the jump height but with less correlation coefficient (r=.69). This implies that the first peak of force has closer relationship to the jump height than the second one. This phenomena seemed to be opposite to the conclusion of James J. Dowling and Lydia Vamos (1993): "the five worst jumps seemed to be characterized by a double peak of force in the positive impulse phase compared to the five best jumps, which seemed to have only one." (p.104).

	P ₀	P ₁	P ₂	p ₀	p ₁	p ₂	I ₁	I_2	T ₀	T ₁	T_2
Mean	-382.8	1039.4	1286.7	52	1.43	1.77	-69.3	331.5	552.8	286.7	103.9
SD	101.7	174.4	217.5	.12	.18	.18	25.7	43.2	72.3	32.1	14.1
R	05	.87*	.69	24	.77*	.51	27	.86*	1	3	.1

Table1	The	Variables	of	Force-Time	Curve

Note. * p<.01.

The positive ground reaction impulse I_2 is 331.5±43.2NS with just as high correlation as the

first peak of force. The negative impulse I_1 with the mean value -69.3NS shows the characteristic of great dispersion. The force-time curve of some performances is too irregular in negative impulse for us to read the force impulse data correctly.

The sequence of joint acceleration: Regarding the sequence of the joint rotational acceleration of volleyball player, it is revealed in figure 2 that the shoulder is first, the hip

second, then the knee and the ankle last. The mean of the time variables is listed in Table 2. The shoulder joint begins acceleration at .59s, but ends at .39s, which means that from .39s to the datum line the shoulder has no rotational acceleration. It is clear that the shoulder is isolated with the other joints when making acceleration. Also the hip joint is double accelerated during the takeoff phase. Within the period of .29s, there is the short period (about .08s) during which no joint angular acceleration is found at the hip joint.

The kinematic variables: The motion of CM is presented in Table 3. The downward motion of

CM is seemed very deep with the mean value .446±041m, which is high negatively related to

the jump height (r=-.84, p<.01). The peak of vertical velocity with the mean value 3.409m/s is emerged at datum line. Because of the arm wave during the takeoff, the hand produced great

velocity with the peak value 12.8±1.3m/s. This hand peak of velocity shows high correlation



(r=.83, p<.01) with jump height.

Figure 2 - The sequence of the joint angular velocity rotational acceleration.

Figure 3 - Typical joint

of VJP of volleyball player.

In aspect of joint rotation, all joints except the shoulder are on the positive peak of angular velocity at the point of datum line (see Figure 3). This implies that the volleyball players have high ability to be coordinate in joint acceleration comparing to the other subjects (Xinhai Shan, etal., 1997).

Table 2	Time Variables of Joint Angular Acceleration
	Time variables of come Angular Acceleration

SHOULDER				HIP			k	NEE	ANKLE		
Ta	Tn	Τs	T_{a1}	T_n	T_{a2}	Т _Н	Ta	Tκ	Ta	T _A	
.20	.39	.59	.11	.08	.1	.29	.21	.21	.13	.13	

Table 3	Biomechanical Variables										
Variables	V_{hand}	Vy	ωs	$\omega_{\rm H1}$	<i>0</i> _{Н2}	<i>0</i> к	ω _A	H_{d}	Hj		
Mean	12.8	3.409	831. 0	264.3	626.3	888.6	755.3	.446	.593		
SD	1.3	.16	98.7	36.9	53.3	66.6	84.8	.041	.033		

Note: The velocities and angular velocities are the maximum values.

CONCLUSION: On the VJP of professional volleyball player, the double peak of force is shown on the force-time curve. The first peak has higher relative to the jump height than the second one though the first peak force is lower than the second peak force. In aspect of the joint rotation, first the shoulder emerges the acceleration, then the hip, next the knee and the last the ankle. Unlike the other joints that emerge the acceleration just in period of upward phase, the shoulder emerges the acceleration mainly in the downward phase. The hip has double rotational accelerations rather than continuous speed up rotation. Further more, the peak of arm waving velocity is high positive correlate with the jump height. Every joint except the shoulder seams to be highly coordinated to reach the maximum angular velocity at the liftoff point It is clear that, the powerful wave of arm, the high strength of hip joint with short downward motion of CM are much more helpful to improve the joint height.

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